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## Introduction to Bayesian Statistical Inference: Comparison and Assumptions

Henry Overos

University of Maryland, College Park

November 8, 2019

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 Increased understanding of the differences between Frequentist and Bayesian approaches to Inference and Modeling

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- Increased understanding of the differences between Frequentist and Bayesian approaches to Inference and Modeling
- Highlight the possible utility of Bayesian approaches in political science research

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- Increased understanding of the differences between Frequentist and Bayesian approaches to Inference and Modeling
- Highlight the possible utility of Bayesian approaches in political science research
- Provide resources for further study or work on this topic

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- Provide resources for further study or work on this topic

## Introduction

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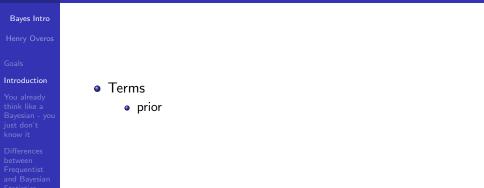
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# What do you think of when you hear about Bayesian Statistics?



The Simple Mechanics o Bayesian Estimation



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Questions?

- prior
- posterior



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Questions?

- prior
- posterior
- subjective

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- prior
- posterior
- subjective
- Controversy?
  - "I'm a closeted Bayesian"

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Questions?

- prior
- posterior
- subjective
- Controversy?
  - "I'm a closeted Bayesian"
  - "It is too hard to explain, especially to Reviewer 2"

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• You read that the bus comes to your stop at 9 am

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- You read that the bus comes to your stop at 9 am
- Day 1 the bus shows up at 9:10

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- You read that the bus comes to your stop at 9 am
- Day 1 the bus shows up at 9:10
- Day 2 the bus shows up at 9:08

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- You read that the bus comes to your stop at 9 am
- Day 1 the bus shows up at 9:10
- Day 2 the bus shows up at 9:08
- Day 3 the bus shows up at 9:16

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- You read that the bus comes to your stop at 9 am
- Day 1 the bus shows up at 9:10
- Day 2 the bus shows up at 9:08
- Day 3 the bus shows up at 9:16
- What do you start doing?

## Bus Example Cont'd

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## Bus Example Cont'd

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- Your **prior** expectation before day 1 is to expect the bus to arrive at exactly 9:00 am
- This prior is largely uninformed you have no data to back up the validity of the claim

## Bus Example Cont'd

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- Your **prior** expectation before day 1 is to expect the bus to arrive at exactly 9:00 am
- This prior is largely uninformed you have no data to back up the validity of the claim
- As the days progress, your expectation becomes more informed by data and you update your expected bus arrival, creating a new understanding of the probability distribution of when the bus is **most likely** to arrive

## Bayes' Theorem

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## What you did with the bus, put more formally

$$P(B_j|A) = \frac{P(B_j)P(A|B_j)}{\sum_{i=1}^k P(B_i)P(A|B_i)}$$

## Bayes' Theorem

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$$P(B_j|A) = \frac{P(B_j)P(A|B_j)}{\sum_{i=1}^k P(B_i)P(A|B_i)}$$

- Named after the Rev. Thomas Bayes (1700-1761) who used conditional probability to estimate unknown parameters
- Also Pierre-Simon Laplace independently formulated a similar relationship between prior and conditional probabilities around the same time

## Bayes' Theorem

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What you did with the bus, put more formally

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- Named after the Rev. Thomas Bayes (1700-1761) who used conditional probability to estimate unknown parameters
- Also Pierre-Simon Laplace independently formulated a similar relationship between prior and conditional probabilities around the same time

The probability that a theory or hypothesis is true **if** some event has occurred

# Predicting Terrorist Attacks Example: Sept. 11 (Nate Silver)

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Questions?

How likely is it that someone intentionally flies a plane into a skyscraper in New York?

# Predicting Terrorist Attacks Example: Sept. 11 (Nate Silver)

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Questions?

How likely is it that someone intentionally flies a plane into a skyscraper in New York?

Before the first plane hit the tower - our prediction that terrorists would fly a plane into a skyscraper was small, say 1 in 20,000 or 0.005 percent. It's possible but not something we would ever really consider.

This is our prior

# Predicting Terrorist Attacks Example: Sept. 11 (Nate Silver)

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Before the first plane hit the tower - our prediction that terrorists would fly a plane into a skyscraper was small, say 1 in 20,000 or 0.005 percent. It's possible but not something we would ever really consider.

## This is our prior

It is also the probability of a terrorist attack given the frequency of occurrences in the observed sample data (20,000 days).

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Questions?

Next, we have to examine the probability of *event, conditioned on the hypothesis being true.* That is, what is the probability that a plane hit a skyscraper, **if** there was a terrorist attack? After the first plane hits, this number is 100 percent. If there are terrorists attacking New York, they're flying the plane into the skyscraper.

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Questions?

We then examine the probability of a plane hitting the tower **if terrorists are not attacking (i.e. accidentally**. Empirically, we can assume the number is 0.008 this because only two planes had hit skyscrapers in New York prior (1945 and 1946 but these were accidents).

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We now have everything we need to predict the likelihood that there is a terror attack occurring when the plane hits:

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$$P(atk) = 0.00005$$

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$$P(atk) = 0.00005$$

$$P(\mathit{crash}|\mathit{atk}) = 1$$

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P(atk) = 0.00005

P(crash|atk) = 1

 $P(crash|\neg atk) = 0.00008$ 

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P(atk|Crash)

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P(atk) = 0.00005

P(crash|atk) = 1

 $P(crash|\neg atk) = 0.00008$ 

P(atk|Crash)

 $= \frac{P(\mathsf{atk})P(\mathsf{Crash}|\mathsf{atk})}{P(\mathsf{atk})P(\mathsf{Crash}|\mathsf{atk}) + P(\neg\mathsf{atk})(\mathsf{Crash}|\neg \mathsf{atk})}$ 

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P(atk) = 0.00005

P(crash|atk) = 1

 $P(crash|\neg atk) = 0.00008$ 

P(atk|Crash)

 $= \frac{P(atk)P(Crash|atk)}{P(atk)P(Crash|atk) + P(\neg atk)(Crash|\neg atk)}$  $= \frac{0.00005 * 1}{0.00005 * 1 + 0.00008 * (1 - 0.00005)}$ 

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Questions?

P(atk) = 0.00005

P(crash|atk) = 1

 $P(crash|\neg atk) = 0.00008$ 

P(atk|Crash)

 $\begin{aligned} & \frac{P(atk)P(Crash|atk)}{P(atk)P(Crash|atk) + P(\neg atk)(Crash|\neg atk)} \\ &= \frac{0.00005 * 1}{0.00005 * 1 + 0.00008 * (1 - 0.00005)} \\ &= \frac{0.00005}{.00005 + 0.0000796} \approx 0.385 \end{aligned}$ 

## Second Plane?

Update our prior:

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$$P(atk) = 0.385$$

Update our prior:

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Questions?

$$P(atk) = 0.385$$

$$P(crash|atk) = 1$$

Update our prior:

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Questions?

$$P(atk) = 0.385$$

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 $P(crash|\neg atk) = 0.00008$ 

Update our prior:

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P(atk) = 0.385

$$P(crash|atk) = 1$$

 $P(crash|\neg atk) = 0.00008$ 

P(atk|Crash)

Update our prior:

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Questions?

P(atk) = 0.385

P(crash|atk) = 1

 $P(crash|\neg atk) = 0.00008$ 

P(atk|Crash)

 $=rac{0.385*1}{0.385*1+0.00008*(1-0.385)}$ 

Update our prior:

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Questions?

P(atk) = 0.385

$$P(crash|atk) = 1$$

 $P(crash|\neg atk) = 0.00008$ 

P(atk|Crash)

 $= \frac{0.385 * 1}{0.385 * 1 + 0.00008 * (1 - 0.385)}$  $= \frac{0.385}{.385 + 0.3850492} \approx 0.999$ 

# Why do we use Statistics?

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## Why do we use Statistics?

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Questions?

# Political Scientists make inferences about the world using a comparatively small sample of data

## Why do we use Statistics?

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Questions?

Political Scientists make inferences about the world using a comparatively small sample of data

- Statistics is used to make inferences about **parameters**, which tend to describe the data-generating process
- We have and observe data but we model the data-generating process

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### Frequentist

• Probability: the relative frequency of an event given a large number of trials

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- Probability: the relative frequency of an event given a large number of trials
- Unknown parameters have a fixed value, we just don't know it

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Questions?

- Probability: the relative frequency of an event given a large number of trials
- Unknown parameters have a fixed value, we just don't know it
- Correct model output provides a level of confidence that, if we were to repeat the experiment or run the model more times, the **true** value of a parameter falls within a certain interval

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Questions?

- Probability: the relative frequency of an event given a large number of trials
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Questions?

### Bayesian

 Probability: Given the evidence and prior knowledge on an event, what degree of certainty do we have that an event will occur?

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Questions?

- Probability: Given the evidence and prior knowledge on an event, what degree of certainty do we have that an event will occur?
- Unknown parameters are not fixed and their "true" value is uncertain

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Questions?

- Probability: Given the evidence and prior knowledge on an event, what degree of certainty do we have that an event will occur?
- Unknown parameters are not fixed and their "true" value is uncertain
- Model provides our level of certainty that the parameter value is inside an interval given the data we have now (Credible Interval)

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Questions?

- Probability: Given the evidence and prior knowledge on an event, what degree of certainty do we have that an event will occur?
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Questions?

Given a parameter  $\beta$ , that describes the data-generating process, how do we make inferences?

### Frequentist

• The Key:  $P(\text{Data}|H_0)$ 

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Questions?

Given a parameter  $\beta$ , that describes the data-generating process, how do we make inferences?

- The Key:  $P(\text{Data}|H_0)$
- Reject  $H_0$  if  $P(\text{Data}|H_0) < 0.05$

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Questions?

Given a parameter  $\beta$ , that describes the data-generating process, how do we make inferences?

- The Key:  $P(\text{Data}|H_0)$
- Reject  $H_0$  if  $P(\text{Data}|H_0) < 0.05$
- Fail to Reject  $H_0$  if  $P(\text{Data}|H_0) \ge 0.05$

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Questions?

Given a parameter  $\beta$ , that describes the data-generating process, how do we make inferences?

### Frequentist

- The Key:  $P(\text{Data}|H_0)$
- Reject  $H_0$  if  $P(\text{Data}|H_0) < 0.05$
- Fail to Reject  $H_0$  if  $P(\text{Data}|H_0) \ge 0.05$

- The Key:  $P(\beta|\text{Data})$
- $P(\beta|\mathsf{Data})$  is what we call the posterior distribution
- $\bullet\,$  The result of a Bayesian model estimation is a probability distribution around the parameter  $\beta\,$

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Questions?

## Deriving the Posterior Distribution of the Parameter

$$\pi(\theta|y) = \frac{p(\theta)L(\theta|y)}{\int_{\theta} p(\theta)L(\theta|y)}$$

$$\propto p(\theta) L(\theta|y)$$

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## Deriving the Posterior Distribution of the Parameter

$$\pi(\theta|y) = \frac{p(\theta)L(\theta|y)}{\int_{\theta} p(\theta)L(\theta|y)}$$

$$\propto p(\theta)L(\theta|y)$$

## Symbol Key

• y: vector of the observed data/outcome variables

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## Deriving the Posterior Distribution of the Parameter

$$\pi(\theta|y) = \frac{p(\theta)L(\theta|y)}{\int_{\theta} p(\theta)L(\theta|y)}$$

 $\propto p(\theta)L(\theta|y)$ 

- y: vector of the observed data/outcome variables
- $\theta$ : the parameter of the data y's distribution

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$$\pi(\theta|y) = \frac{p(\theta)L(\theta|y)}{\int_{\theta} p(\theta)L(\theta|y)}$$

 $\propto p(\theta)L(\theta|y)$ 

- y: vector of the observed data/outcome variables
- $\theta$ : the parameter of the data y's distribution
- $\pi$ : posterior

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 $\propto p(\theta)L(\theta|y)$ 

- y: vector of the observed data/outcome variables
- $\theta$ : the parameter of the data y's distribution
- $\pi$ : posterior
- $\pi(\theta|y)$ : The Posterior Distribution of  $\theta$

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 $\propto p(\theta)L(\theta|y)$ 

- y: vector of the observed data/outcome variables
- $\theta$ : the parameter of the data y's distribution
- $\pi$ : posterior
- $\pi(\theta|y)$ : The Posterior Distribution of  $\theta$
- $p(\theta)$ : The Prior Distribution of  $\theta$

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## Deriving the Posterior Distribution of the Parameter

$$\pi(\theta|y) = \frac{p(\theta)L(\theta|y)}{\int_{\theta} p(\theta)L(\theta|y)}$$

 $\propto p(\theta)L(\theta|y)$ 

- y: vector of the observed data/outcome variables
- $\theta$ : the parameter of the data y's distribution
- $\pi$ : posterior
- $\pi(\theta|y)$ : The Posterior Distribution of  $\theta$
- $p(\theta)$ : The Prior Distribution of  $\theta$
- L(θ|y): The Likelihood function of the outcome y, given the parameter θ

# THIS IS IT

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# $\pi(\theta|y) \propto p(\theta) L(\theta|y)$

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# $\pi(\theta|y) \propto p(\theta) L(\theta|y)$

The posterior distribution of the parameter we are interested in is equivalent to the prior distribution of the parameter times the likelihood of getting that parameter given the data that we have

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Questions?

# $\pi(\theta|y) \propto p(\theta) L(\theta|y)$

The posterior distribution of the parameter we are interested in is equivalent to the prior distribution of the parameter times the likelihood of getting that parameter given the data that we have

As we get more data, the importance of the prior will diminish

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The Simple Mechanics of Bayesian Estimation

Questions?

# Ryan Bakker & Johannes Karreth (2019)

### Lecture Notes and Slides

Introduction to Bayesian Modeling for the Social Sciences, ICPSR 2019.

Andrew Gelman, John B. Carlin, Hal S. Stern, David B. Dunson, Aki Vehtari, & Donald B. Rubin (2013) Bayesian Data Analysis (Third Edition)

## Nate Silver (2012)

The Signal and the Noise: Why so many Predictions Fail - and Some Don't

#### Bayes Intro

Henry Overos

Goals

Introduction

You already think like a Bayesian - you just don't know it

Differences between Frequentist and Bayesian Statistics

The Simple Mechanics o Bayesian Estimation

Questions?

# Thank You!